TECHNIQUES TO MAPPING HOMOGENEOUS PROCESSES IN HETEROGENEOUS ENVIRONMENTS

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INTRODUCTION

Until now, a lot of sofware has been developed for homogeneous systems.

✤Now, heterogeneous systems.

♦ Complex Problems _____

To rewrite sofware

Two options

 $^{>}$ Mapping routines in heterogeneous

systems.

To Paralell

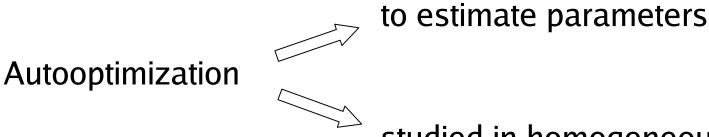
To Paralell _____ To Estimate _____ To Build mathematical parameters modell execution time

INTRODUCTION

Execution Time Estimation:

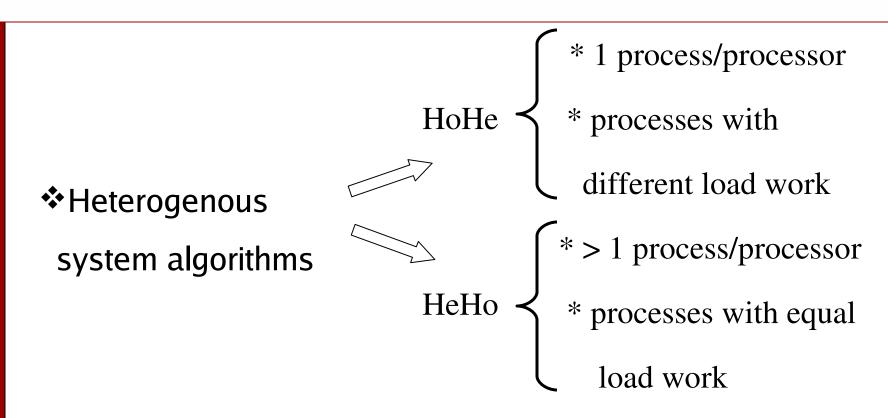
$$t_{exe} = f(n, SP, AP)$$

- n = problem size
- SP = system parameters
- AP = algorithm parameters



studied in homogeneous

INTRODUCTION



HeHo better: no to rewrite routines

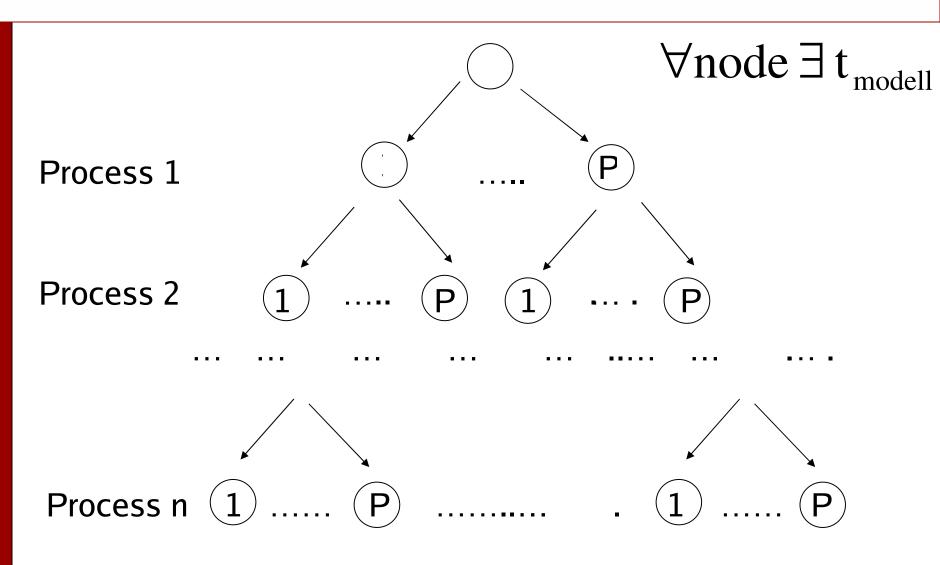
In parallel computing, assign processes to processors in order to obtain a mapping which reduces execution time.

Efficient and optimal solutions for some particular problems.

For other problems approximate solutions are obtained with heuristic methods.

The assignation was studied for a parallel dynamic programming scheme and for dense linear algebra factorizations.

The problem is solved by searching through an assignation tree.



✤Mapping processes (1...n) to processors (1...P).

The search through the tree:

- Backtracking
- Backtracking by pruning nodes
- Branch and Bound
- Greedy methods



A large amount of time is consumed (Backtracking)

Solution obtained far from the optimum (greedy method, backtracking by pruning nodes, ...)

*We consider parallel iterative schemes.

A large variety of problems: dynamic programming, graph algorithms, genetic algorithms...

Additionally, the method can be applied to other problems and schemes, as for example linear algebra factorizations.

The theoretical model requires a precise knowledge of system parameters like basic arithmetic operations time, or sending and start-up times of a communication.

Modelled execution time

$$t(s,D) = \underbrace{t_c * t_{comp}(s,D)}_{t_c * t_{comp}(s,D)} + \underbrace{t_{comm}(s,D)}_{t_c * t_{comm}(s,D)}$$

computation communication

- s: problem size
- D: number of processes used in the solution
- t_c: cost of a basic arithmetic operation
- t_{comp}: number of basic arithmetic operations
- t_{comm}: communication cost
- It is easy to represent computation part.

It is frequently difficult to represent communication part: some adjust by least square.

POSSIBLE SOLUTIONS

To use traditional techniques in trees to achieve a good solution, but this consumes a large amount of time.

Even with strategies to prune nodes in the tree.

To use heuristic techniques sucessfully applied to solve other hard optimization problems, like Scatter Search.

Scatter Search: heuristic technique by which different generations of a initial population is possible to achieve a good solution of a problem.

Basic Scatter Search Scheme:

- 1. generate initial population
- 2. while convergence is not reached
- 3. element selection to be combined
- 4. combining of selected elements
- 5. inclusion of the most promising elements in the population

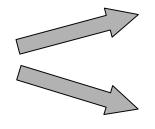
6. inclusion in the population of the most scattered elements with respect to the most promising elements

7.endwhile

A large number of different schemes of scatter search in order to apply our problem.

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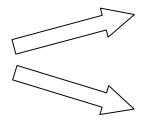
A.- Initial population



Initial assignation of processes to processors randomly: AA Initial assignation of processes to processors considering number of processors: AC

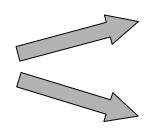
A large number of different schemes of scatter search in order to apply our problem.

A.- Initial population



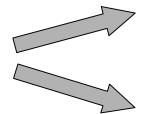
Initial assignation of processes to processors randomly: AA Initial assignation of processes to processors considering number of processors: AC

B.- To select elements to combine



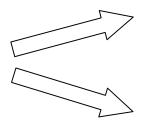
All elements of population vs all elements: **TT** Best elements of population vs worst elements: **MP**

C.- To include the most scattered respect to the most promising



To include elements with longest distance to most promising elements: **MF** To include elements which are more "different" with respect to promising elements: **MD**

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To include elements with longest distance to most promising elements: **MF** To include elements which are more "different" with respect to promising elements: **MD**



The best of the new solutions are not better than the best of the older ones: **MM** The average of new solutions is not better than old ones: **MA**

RESULTS

✤Best scheme with options of initial reference set: AC and convergence reached: MA.

DIFFERENT OPTIONS OF SCATTER SEARCH SCHEME VERSUS BACKTRACKING WITH PRUNING

B Combine C Include	TT	MP
MF	90%	85%
MD	91%	86%

Best scheme with optiones: TT-MD

RESULTS

✤REAL TIMES IN KIPLING

SIZE	COMPLEXITY	ANOTHER TECHNIQUES	SCATTER SEARCH
SMALL [1100.000	SMALL	82%	18%
	BIG	80%	20%
MEDIUM [100.000500.000]	SMALL	63%	37%
	BIG	59%	41%
BIG [500.0001.000.000]	SMALL	52%	48%
	BIG	47%	53%

TABLE WITH COMPARISONS AMONG TRADITIONAL TECHNIQUES AND SCATTER SEARCH TO ESTIMATE THE BEST MAPPING OF PROCESSES TO PROCESSORS

RESULTS

SIMULATIONS TIMES

SIZE	COMPLEXITY	ANOTHER TECHNIQUES	SCATTER SEARCH
SMALL [1100.000	SMALL	91%	9%
	BIG	73%	27%
MEDIUM [100.000500.000]	SMALL	42%	58%
	BIG	40%	60%
BIG [500.0001.000.000]	SMALL	22%	78%
	BIG	5%	95%

TABLE WITH COMPARISONS AMONG TRADITIONAL TECHNIQUES AND SCATTER SEARCH TO ESTIMATE THE BEST MAPPING OF PROCESSES TO PROCESSORS

FUTURE WORKS

SCATTER SEARCH IS A PROMISING TECHNIQUE TO MAPPING IN HETEROGENEOUS SYSTEMS.

✤TO APPLY ANOTHER HEURISTIC TECHNIQUES, LIKE TABU SEARCH, GENETIC ALGORITHMSA. ND TO STUDIE APPLICATIONS TO ANOTHER PARALELL ALGORITHMS SCHEMES

♦ OUR FINAL GOAL IS THE SOFTWARE MUST DECIDE HOW TO MAPPING AN HOMOGENEOUS ALGORITHM IN AN HETEROGENEOUS SYSTEMS, DEPENDIND ON DIFFERENT ALGORITHMS AND SYSTEM PARAMETERS.